JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY KAKINADA
KAKINADA – 533 003, Andhra Pradesh, India
DEPARTMENT OF ELECTRONICS AND COMMUNICATION ENGINEERING

II Year-II Semester		L	T	P	C
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LINEAR CONTROL SYSTEMS					

Course objectives:

- To introduce the concepts of open loop and closed loop systems, mathematical models of mechanical and electrical systems, and concepts of feedback
- To study the characteristics of the given system in terms of the transfer function and introducing various approaches to reduce the overall system for necessary analysis
- To develop the acquaintance in analyzing the system response in time-do main and frequency domain in terms of various performance indices
- Toanalyzethesystem in terms of absolute stability and relative stability by different approaches
- To design different control systems for different applications as per given specifications
- To introduce the concepts of state variable analysis, design and also the concepts of controllability and observability.

UNIT I - INTRODUCTION

Concepts of System, Control Systems: Open Loop and closed loop control systems and their differences. Different examples of control systems, Feed-Back Characteristics, Effects of feedback. Mathematical models, Differential equations, Impulse Response and transfer functions. Translational and Rotational mechanical systems

UNIT II – TRANSFER FUNCTION REPRESENTATION

Transfer Function of DC Servo motor - AC Servo motor- Synchro-transmitter and Receiver, Block diagram representation of systems considering electrical systems as examples –Block diagram algebra–Representation by Signal flowgraph-Reduction using mason's gain formula.

TIME RESPONSE ANALYSIS

Standard test signals – Time response of first order systems – Characteristic Equation of Feedback controlsystems, Transient response of second order systems – Time domain specifications – Steady state response - Steady stateerrors and error constants.

UNIT III – STABILITY ANALYSIS IN S-DOMAIN

The concept of stability – Routh's stability criterion – qualitative stability and conditional stability – limitations of Routh's stability100

Root Locus Technique:

The root locus concept - construction of root loci-effects of adding poles and zeros to G(s) H(s) on the root loci.

UNIT IV

Frequency response analysis: Introduction, Correlation between time and frequency response, PolarPlots, BodePlots,Nyquist Stability Criterion

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UNIT V – CLASSICAL CONTROL DESIGN TECHNIQUES

Compensation techniques – Lag, Lead, Lead-Lag Controllers design infrequency Domain, PIDControllers. State Space Analysis of Continuous Systems Concepts of state, state variables andstate model, derivation ofstate models from block diagrams, Diagonalization- Solving the Timeinvariant state Equations- State Transition Matrix and it's Properties – Concepts of ControllabilityandObservability.

TEXT BOOKS:

1. Automatic Control Systems 8th edition– by B.C.Kuo – Johnwiley and son's, 2003.
2. Control Systems Engineering –by I. J.Nagrathand M.Gopal, New Age International (P) Limited, Publishers, 2nd edition, 2007
3. Modern Control Engineering–by Katsuhiko Ogata–Pearson Publications, 5th edition, 2015.

REFERENCE BOOKS:

1. Control Systems by A.Nagoorkani, RB Apublications, 3 edition, 2017.
2. Control Systems by A.Anandkumar, PHI, 2 Edition, 2014.

Course Outcomes:

- This course introduces the concepts of feedback and its advantages to various control systems
- The performance metrics to design the control system intime-domain and frequency domain are introduced.
- Control systems for various applications can be designed using time-domain and frequency domain analysis.
- In addition to the conventional approach, the state space approach for the analysis of control systems is also introduced.